

$$\vec{F} = \dot{\vec{p}} = \vec{B} \times \vec{v}$$

~~$$\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$$~~

$$\frac{d}{dt} \left( \frac{\dot{x} \cdot m}{\sqrt{1 - \dot{x}^2/c^2}} \right) = q(\vec{E} + \dot{x} \times \vec{B})$$

$$P_0 \cos(\omega t) = \frac{q b}{\sqrt{1 + \frac{p^2}{c^2}}} \cos(\omega t)$$

halfway through deriving the Lorentz force law I remembered google

$$\dot{\vec{p}} = q(\vec{E} + \vec{v} \times \vec{B}) \quad p = \frac{\gamma m v}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$v^2 \left( 1 + \frac{p^2}{c^2} \right) = p^2$$

$$p_x = p_0 \cos\left(\frac{q b t}{\sqrt{m^2 + \frac{p^2}{c^2}}}\right)$$

$$p_y = p_0 \sin\left(\frac{q b t}{\sqrt{m^2 + \frac{p^2}{c^2}}}\right)$$

$$p_x = p_0 \cos\left(\frac{q b t}{\sqrt{c^2 + p^2}}\right) \quad p_y = p_0 \sin\left(\frac{q b t}{\sqrt{c^2 + p^2}}\right)$$

$$\vec{p} = q \left( \vec{E} + \frac{\vec{p} \times \vec{B}}{\sqrt{1 + \frac{p^2}{c^2}}} \right)$$

$$E = \sqrt{p^2 + m^2}$$

$$\vec{v} = \frac{\vec{p}}{\sqrt{1 + \frac{p^2}{c^2}}}$$

$$E^2 = p^2 c^2 + m^2 c^4$$

$$\frac{E^2 - m^2 c^4}{c^2} = p^2$$

$$\dot{p} = \frac{q}{\sqrt{1 + \frac{p^2}{c^2}}} (p \times B)$$

$$B = \begin{bmatrix} 0 \\ 0 \\ b \end{bmatrix}$$

$$p = \begin{bmatrix} p_x \\ p_y \\ 0 \end{bmatrix}$$

$$p \times B = \begin{bmatrix} -b p_y \\ b p_x \\ 0 \end{bmatrix}$$

$$\frac{E^2}{c^4} - m^2 = \frac{p^2}{c^2}$$

$$p_0 = \frac{1}{c} \sqrt{E^2 - m^2 c^4}$$

$$\vec{v} = \frac{\vec{p}}{\sqrt{1 + \frac{p^2}{c^2}}}$$

$$p^2 = v^2 \left( m^2 + \frac{p^2}{c^2} \right)$$

$$\dot{p}_x = \frac{-q b p_y}{\sqrt{1 + \frac{p_x^2 + p_y^2}{c^2}}} \quad p_y$$

$$\dot{p}_y = \frac{q b p_x}{\sqrt{1 + \frac{p_x^2 + p_y^2}{c^2}}} \quad p_x$$

some important ODE's

arrange so you don't feel weird without the admittedly redundant

$$p_x = p_0 \cos(\omega t) \quad p_y = p_0 \sin(\omega t)$$

$$\omega \sin(\omega t) = \frac{+q b}{\sqrt{1 + \frac{p^2}{c^2}}} (p_y)$$

$$\frac{p}{\sqrt{m^2 + \frac{p^2}{c^2}}} = \frac{p}{\sqrt{1 + \left(\frac{p}{c}\right)^2}} = v$$

$$\frac{p c}{\sqrt{m^2 c^2 + p^2}}$$

$$\omega = \frac{q b}{\sqrt{1 + \frac{p^2}{c^2}}}$$

$$\frac{q b}{\sqrt{m^2 + \frac{p^2}{c^2}}}$$

$$\frac{q b}{\sqrt{m^2 + \frac{E^2}{c^4}}}$$

$$\vec{v} = \frac{\vec{p}}{\sqrt{m^2 + \frac{p^2}{c^2}}} =$$

$$v_0 = \frac{1}{c} \sqrt{E^2 - m^2 c^4} \left( \frac{c^2}{E} \right) = \sqrt{1 - \frac{m^2 c^4}{E^2}} = v_0$$

$$v_x = p_0 \left( \frac{1}{\sqrt{m^2 + \frac{p^2}{c^2}}} \right) \cos(\omega t) = v_0 \cos(\omega t)$$

$$x(t) = \frac{v_0}{\omega} \sin(\omega t) + x_0$$

$$y(t) = -\frac{v_0}{\omega} \cos(\omega t) + y_0$$

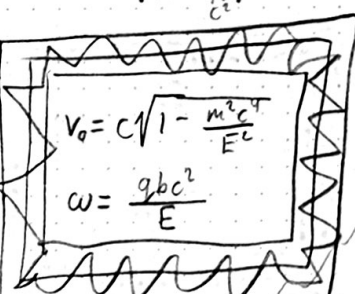


at this point I gave up on doing everything by hand and started using mathematica

$$p_x = p_0 \cos\left(\frac{q b c^2}{E} t\right)$$

$$p_y = p_0 \sin\left(\frac{q b c^2}{E} t\right)$$

$$v_y = p_0 \left( \frac{1}{\sqrt{m^2 + \frac{p^2}{c^2}}} \right) \sin(\omega t) = v_0 \sin(\omega t)$$



$$x_1(t) = \frac{v_0}{\omega} \sin(\omega t)$$

$$y_1(t) = -\frac{v_0}{\omega} \cos(\omega t) + \frac{v_0}{\omega}$$

$$x_2(t) = \frac{v_0}{\omega} \sin(\omega t)$$

$$y_2(t) = -\frac{v_0}{\omega} \cos(\omega t) + \frac{v_0}{\omega}$$

$$d(t) = \sqrt{\frac{v_0^2}{\omega^2} [\sin(\omega t_1 - \sin(\omega t_2))]^2 + \frac{v_0^2}{\omega^2} [\cos(\omega t_1) - \cos(\omega t_2) - \frac{v_0}{\omega_1} + \frac{v_0}{\omega_2}]^2}$$

$$d(t) = \sqrt{\left( \frac{v_0}{\omega_1} \sin(\omega t) - \frac{v_0}{\omega_2} \sin(\omega t) \right)^2 + \left( \frac{v_0}{\omega_1} [\cos(\omega t) - 1] - \frac{v_0}{\omega_2} [\cos(\omega t) - 1] \right)^2}$$

$$d(t) \approx d(0) + \dot{d}(0) t + \frac{1}{2} \ddot{d}(0) t^2$$

cause we're working with times that are tiny compared with all other variables in the problem

unfortunately we need more terms... it is not and d(t) isn't full not depending on mag

↑ DON'T FORGET ↑ THESE DEFINITIONS!

$$\partial_t \vec{\psi} = \hat{H} \vec{\psi}$$

$$\vec{\psi}(x, t) = \int \hat{K}(x, x_0, t) \psi(x_0, 0) dx_0$$

$$\hat{x} = [\hat{x}, \hat{H}]$$

$$\hat{x}(t) \hat{K}(x, x_0, t) = x_0 \hat{K}(x, x_0, t)$$

method for solving linear PDE's

Definition of inner product

$$\langle \text{final state} | \text{initial state} \rangle = (\text{amplitude})$$

I've had this backward for 500000 long...

$$[x, p] = i\hbar$$

$$p \Rightarrow -i\hbar \frac{\partial}{\partial x}$$

$$\int f'g + g'f dx = fg$$

$$\int f'g dx = -\int g'f dx$$

$$\langle \psi_1 | p | \psi_2 \rangle = \int \psi_1^*(x) [-i\hbar \frac{\partial}{\partial x} \psi_2(x)] dx$$

$$\int \psi_1^*(x + \epsilon i) \psi_2(x) e^{\frac{i\epsilon}{\hbar} x} dx$$

$$\iint \psi_1^*(x + \epsilon i) \psi_2(x) \frac{\partial}{\partial x} e^{\frac{i\epsilon}{\hbar} x(x + \epsilon i)} dx d\epsilon$$

$$\iint \psi_1^*(x + \epsilon i) \psi_2(x) \frac{\partial}{\partial x} e^{\frac{i\epsilon}{\hbar} x(x + \epsilon i)} dx d\epsilon$$

$$-\frac{i\hbar}{\epsilon} \iint \psi_1^*(x + \epsilon i) \psi_2(x) \frac{\partial}{\partial x} e^{\frac{i\epsilon}{\hbar} x(x + \epsilon i)} dx d\epsilon$$

$$+\frac{i\hbar}{\epsilon} \iint \psi_1^*(x) \psi_2(x)$$

$$i\hbar \int \psi_1^*(x) \psi_2(x) dx$$

$$\int -i\hbar \psi_1^*(x) \psi_2'(x) dx$$

WAM!  
IT WORKS!!

$$\langle \psi_2 | \psi_1 \rangle = \int \psi_2^*(x(t)) \psi_1(x(0)) e^{\frac{iS(x)}{\hbar}} dx$$

1D fluid flow:

$$\partial_t v = -\partial_x p$$

$$\partial_t p = -\partial_x v$$

$$15) = \begin{bmatrix} v \\ p \end{bmatrix} \quad \mathbf{I} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\partial_t 15) = -\partial_x \mathbf{I} 15)$$

$$\partial_t 15) = -\mathbf{I} \partial_x 15)$$

$$\partial_t 15) = 2i\pi k \mathbf{I} 15)$$

$$15) = e^{2i\pi k \mathbf{I} t} 15_0$$

$$15(x, z) = F^{-1} [e^{2i\pi k \mathbf{I} t} 15(x, 0)]$$

$$e^{2i\pi k \mathbf{I} t} = \frac{1}{2} \begin{bmatrix} e^{2i\pi k t} & -e^{-2i\pi k t} \\ e^{2i\pi k t} & e^{-2i\pi k t} \end{bmatrix}$$

$$e^{[a \ 0] t} = \frac{1}{2} \begin{bmatrix} e^{at} + e^{-at} & e^{at} - e^{-at} \\ e^{at} - e^{-at} & e^{at} + e^{-at} \end{bmatrix}$$

$$[0 \ a] t = \begin{bmatrix} 0 & 1 \\ a & 0 \end{bmatrix}$$

$$[0 \ 1] t = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & a \\ a & 0 \end{bmatrix}^n = \begin{cases} \begin{bmatrix} a^n & 0 \\ 0 & a^n \end{bmatrix} & \frac{1}{2} n \in \mathbb{Z} \\ \begin{bmatrix} 0 & a^n \\ a^n & 0 \end{bmatrix} & \frac{1}{2} n \notin \mathbb{Z} \end{cases}$$

$$F^{-1} \left[ \begin{bmatrix} \delta(x+z) - \delta(x-z) & \delta(x+z) + \delta(x-z) \\ \delta(x+z) + \delta(x-z) & \delta(x+z) - \delta(x-z) \end{bmatrix} * \begin{bmatrix} p_0 \\ p_0 \end{bmatrix} \right] = \begin{bmatrix} \frac{1}{2}(v_0(x+z) - v_0(x-z)) + \frac{1}{2}(p_0(x+z) + p_0(x-z)) \\ \frac{1}{2}(v_0(x+z) + v_0(x-z)) + \frac{1}{2}(p_0(x+z) - p_0(x-z)) \end{bmatrix}$$

$$v(x, z) = \frac{1}{2}(v(x+z, 0) + v(x-z, 0) + p(x+z, 0) - p(x-z, 0))$$

$$p(x, z) = \frac{1}{2}(p(x+z, 0) + p(x-z, 0) + v(x+z, 0) - v(x-z, 0))$$

complete solution for 1D fluid flow ↑

$$f + af = c \quad f = \sqrt{-af^2 + cf + D}$$

$$f = -af + c \quad \int \frac{1}{\sqrt{-f^2 + f + D}} df = \sqrt{a} t$$

$$f = \sqrt{2(-\frac{1}{2}af^2 + cf + D)}$$

$$\int \frac{1}{\sqrt{f^2 + cf + D}} df = \sqrt{-a} t$$

$$\int \frac{1}{\sqrt{(f+c)^2 + D - c^2}} df = \sqrt{-a} t$$

$$u = f + c$$

$$du = df$$

$$\int \frac{1}{\sqrt{u^2 + D}} du = \sqrt{-a} t$$

$$\int \frac{1}{\sqrt{D - u^2}} du = \sqrt{a} t$$

$$\dot{f} = af + c$$

$$f = af + c$$

$$\dot{f} = af + c$$

$$\dot{g} = ag + c$$

$$g = f + C_2 t^2$$

$$f + C_2 t^2$$

$$f + at + c$$

$$af + c$$

$$f - af = c$$

$$f + 2i\sqrt{a}f - af$$

$$f = -af + c$$

$$f + af = c$$

$$f + 2\sqrt{a}f + af = c + 2\sqrt{a}f$$

$$e^{\sqrt{a}t} f + 2e^{\sqrt{a}t} f + e^{\sqrt{a}t} f = ce^{\sqrt{a}t} + 2\sqrt{a}fe^{\sqrt{a}t}$$

$$\frac{d}{dt}(e^{\sqrt{a}t} f) = ce^{\sqrt{a}t}$$

1D fluid flow (alternate model):

$$\partial_t v = -\partial_x p$$

$$\partial_t p = v$$

$$\partial_t^2 v = -\partial_x^2 v$$

$$\partial_t^2 p = -\partial_x^2 p + f$$

$$f = v$$

$$f = v$$

$$\partial_t^2 \hat{f} = -4a^2 k^2 \hat{f} + \hat{f}$$

$$\partial_t v = -\partial_x p$$

$$\partial_t p = -\partial_x v$$

$$\partial_t^2 v = -\partial_x^2 v$$

$$\partial_t^2 p = -\partial_x^2 p + f$$

$$\partial_t^2 \hat{f} = -\partial_x^2 \hat{f} + f(x)$$

$$p_0 = \text{dat}(H F_0)$$

$$x^2 + bx + c$$

$$x^2 + bx + \frac{b^2}{4} + c - \frac{b^2}{4}$$

$$(x + \frac{b}{2})^2 + c - \frac{b^2}{4}$$

$$\int \frac{1}{\sqrt{b}} du \quad \int \frac{1}{\sqrt{1-u^2}} du$$

$$v = \frac{u}{\sqrt{D}}$$

$$dv = du \cdot \frac{1}{\sqrt{D}}$$

$$du = \sqrt{D} dv$$

$$\ddot{x} = -y$$



Equilibrium  $= 0$

$$\ddot{y} = -ky$$

$$\ddot{y} = -ky$$

$$\dot{y} = \sqrt{2(-\frac{k}{2}y^2 + C)}$$

$$\dot{y} = \sqrt{-ky^2 + C}$$

$$\dot{y} = \sqrt{k} \cdot \sqrt{C - y^2}$$

$$\int \frac{1}{\sqrt{C - y^2}} dy = \int \sqrt{k} dt$$

$$\int \frac{1}{\sqrt{C}} \cdot \frac{1}{\sqrt{1 - (\frac{y}{\sqrt{C}})^2}} dy = \sqrt{k} t$$

$$u(x) = \frac{x}{\sqrt{C}}$$

$$\int \frac{du}{\sqrt{1-u^2}} \cdot \frac{du}{dy} dy = \sqrt{k} t$$

$$\int \frac{1}{\sqrt{1-u^2}} du = \sqrt{k} t$$

$$\sin^{-1}(u) + D = \sqrt{k} t$$

$$\sin^{-1}\left(\frac{y}{\sqrt{C}}\right) + D = \sqrt{k} t$$

$$\frac{y}{\sqrt{C}} = \sin(\sqrt{k} t)$$

$$y(t) = \sqrt{C} \sin(\sqrt{k} t + D)$$

general solution

$$y(t) = \sqrt{C} \sin(\sqrt{k} t + D)$$

$$\dot{y}(t) = \sqrt{k} C \cos(\sqrt{k} t + D)$$

$$y_0 = \sqrt{C} \sin(D)$$

$$\dot{y}_0 = \sqrt{k} C \cos(D)$$

$$y_0^2 = C \sin^2(D)$$

$$\sin^2(D) = \frac{1 - \cos(2D)}{2}$$

$$2y_0^2 = C - C \cos(2D)$$

$$2y_0^2 - C = -C \cos(2D)$$

$$C - 2y_0^2 = C \cos(2D)$$

$$1 - \frac{2}{C} y_0^2 = \cos(2D)$$

$$D = \frac{\cos^{-1}\left(1 - \frac{2}{C} y_0^2\right)}{2}$$

$$2y_0^2 = kC + kC \cos(2D)$$

$$2y_0^2 = kC + kC \left(1 - \frac{2}{C} y_0^2\right)$$

$$2y_0^2 = kC + kC - 2ky_0^2$$

$$4y_0^2 = 2kC - 2ky_0^2$$

$$kC = y_0^2 + ky_0^2$$

$$C = \frac{y_0^2}{k} + y_0^2$$

$$1 - \frac{2}{C} y_0^2 = 1 - \frac{2}{\frac{y_0^2}{k} + y_0^2}$$

~~$$y(t) = \sqrt{\frac{y_0^2}{k} + y_0^2} \sin\left(\sqrt{k} t + \cos^{-1}\left(1 - \frac{2}{C} y_0^2\right)\right)$$

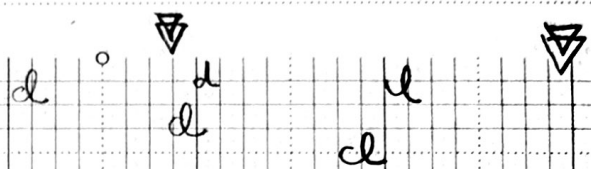
potential (and very painful).  
tailored solution~~

$$y(t) = \sqrt{\frac{y_0^2}{k} + y_0^2} \sin\left(\sqrt{k} t + \frac{1}{2} \cos^{-1}\left(1 - \frac{2}{\frac{y_0^2}{k} + y_0^2} y_0^2\right)\right)$$

even more painful solution

$$y(t) = \sqrt{\frac{y_0^2}{k} + y_0^2} \sin(\sqrt{k} t + D)$$

$$g: \{f: \mathbb{R}^2 \rightarrow \mathbb{R}\} \rightarrow \mathbb{R}$$



$$\nabla_f g[f]$$

$$g[f] = \int_{-1}^1 \int_{-1}^1 f(x,y) dx dy$$

$$\nabla_f g[f] := \left. \frac{d}{dq} \int_{-1}^1 \int_{-1}^1 f(x,y) + q \delta(x-\alpha, y-\beta) dx dy \right|_{q=0}$$

$$\nabla_f g[f](\vec{\alpha}) := \left. \partial_q g[f(\vec{x}) + q \delta(\vec{x} - \vec{\alpha})] \right|_{q=0}$$

$$\frac{d}{dt} [f(t) + s(t-\alpha)] = f'(t) + s'(t-\alpha) \quad \frac{d}{dq} \int_{-1}^1 \int_{-1}^1 f(x,y) dx dy + \frac{d}{dq} q \int_{-1}^1 \int_{-1}^1 \delta(x-\alpha, y-\beta)$$

$$\nabla_f g[f] = 1$$

and this works too!

$$A(x) = \int_a^b L(x, \dot{x}) dt$$

$$\nabla_x A(x) = 0$$

$$f: \mathbb{R} \rightarrow \mathbb{R}$$

$$\nabla_f g[f, f'] := \left. \partial_q g[f(t) + \delta(t-\alpha), f'(t) + \delta'(t-\alpha)] \right|_{q=0}$$

$$\partial_q \int_a^b L(x(\tau) + q \delta(\tau-t), \dot{x}(\tau) + q \delta'(\tau-t)) d\tau$$

stationary point:  $\nabla_f g[f] = 0$

$$t \in [a, b]$$

$$\int_a^b f(\tau) \delta'(\tau-x) d\tau = -f'(x)$$

$$\lim_{h \rightarrow 0} \int_a^b \frac{f(\tau) \delta(\tau-x+h) - f(\tau) \delta(\tau-x)}{h}$$

$$\lim_{h \rightarrow 0} \frac{f(x-h) - f(x)}{h} = -f'(x)$$

$$\partial_q \int_a^b L(x(\tau) + q \delta(\tau-t), \dot{x}(\tau) + q \delta'(\tau-t)) d\tau \Big|_{q=0}$$

$$\int_a^b \frac{\partial L}{\partial x} \cdot \delta(\tau-t) + \frac{\partial L}{\partial \dot{x}} \cdot \delta'(\tau-t) d\tau = 0$$

$$\frac{\partial L}{\partial x} - \frac{d}{dt} \frac{\partial L}{\partial \dot{x}} = 0$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{x}} = \frac{\partial L}{\partial x}$$

yippy! It works!